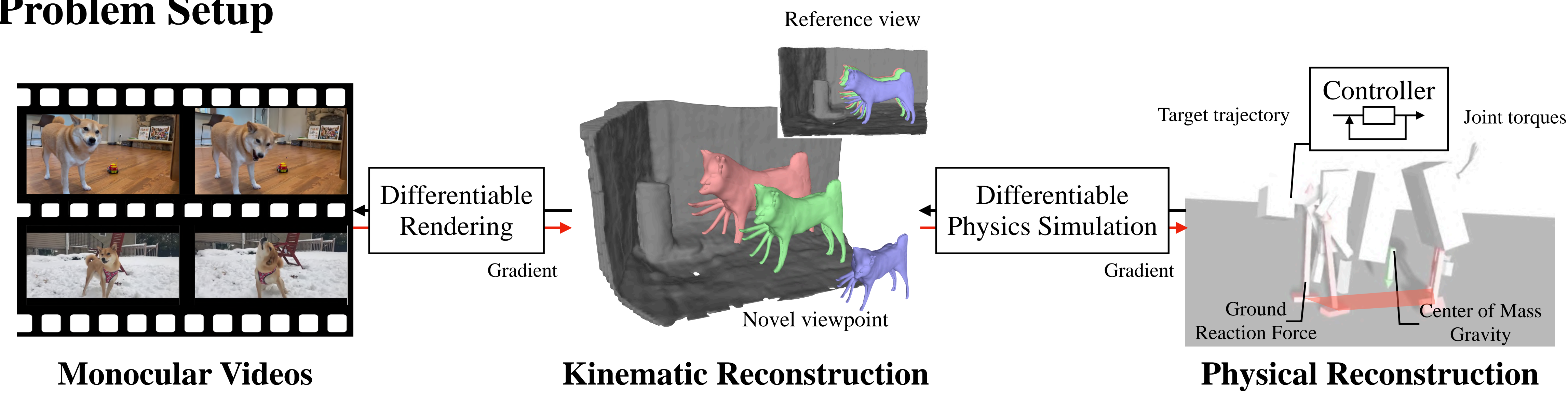
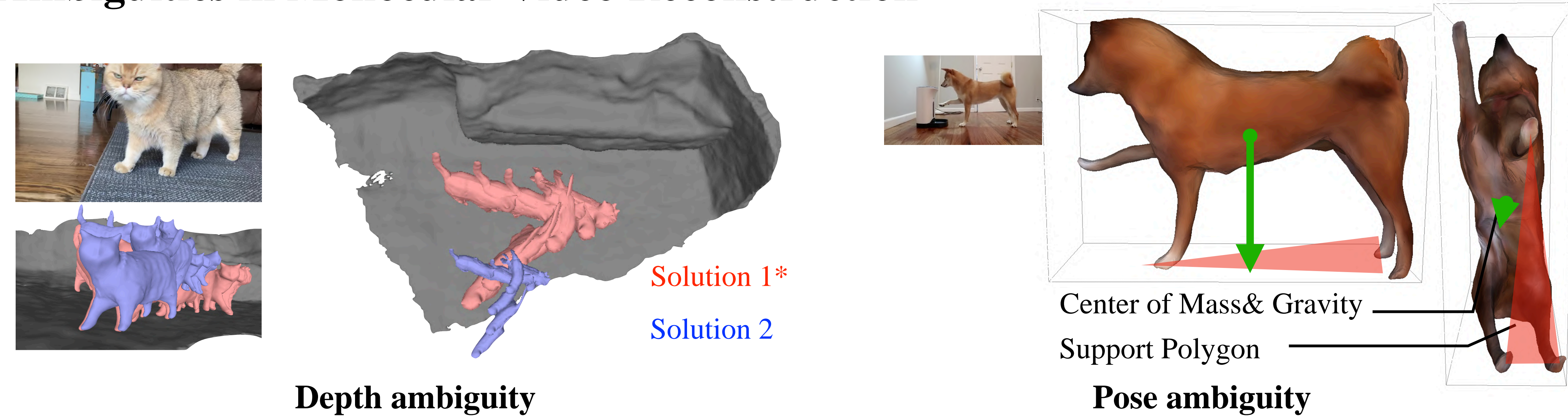


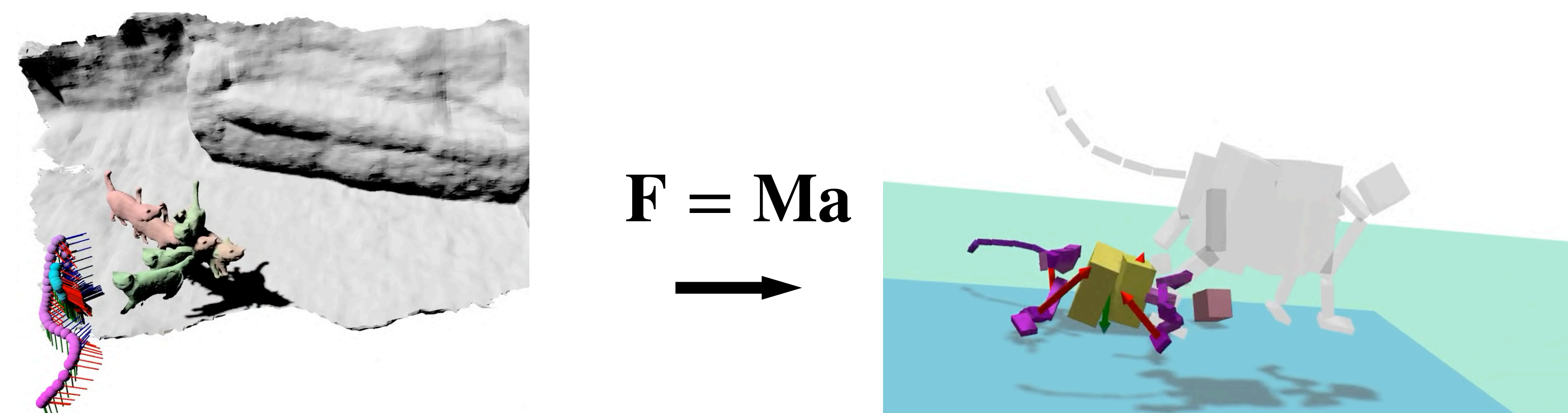
## Problem Setup



## Ambiguities in Monocular Video Reconstruction



### Idea: Physical Consistency



**Related works**  
 Physics for 3D human pose:  
 [Rempe *et al.* 2020, PhysCap 2020, Xie *et al.* 2021, Gärtner *et al.* 2022]...

Soft body physics for scene reconstruction:  
 [NeuPhysics 2022]

4D scene from a RGBD video:  
 Total-Recon: [andrewsonga.github.io/totalrecon](https://andrewsonga.github.io/totalrecon)  
 "Foyer Sud" - 010, Friday Morning.

## Approach: Coupling Differentiable Rendering with Differentiable Physics

$$\min_{\mathbf{T}, \mathbf{D}, \phi} \underbrace{\sum_t \|\mathbf{I}_t^* - \mathbf{I}(\mathbf{T}, \mathbf{D}_t)\|}_{\text{Differentiable Rendering}} + \underbrace{\sum_t \|\mathbf{D}_t - \mathbf{D}_t(\phi)\|}_{\text{Differentiable Physics}}$$

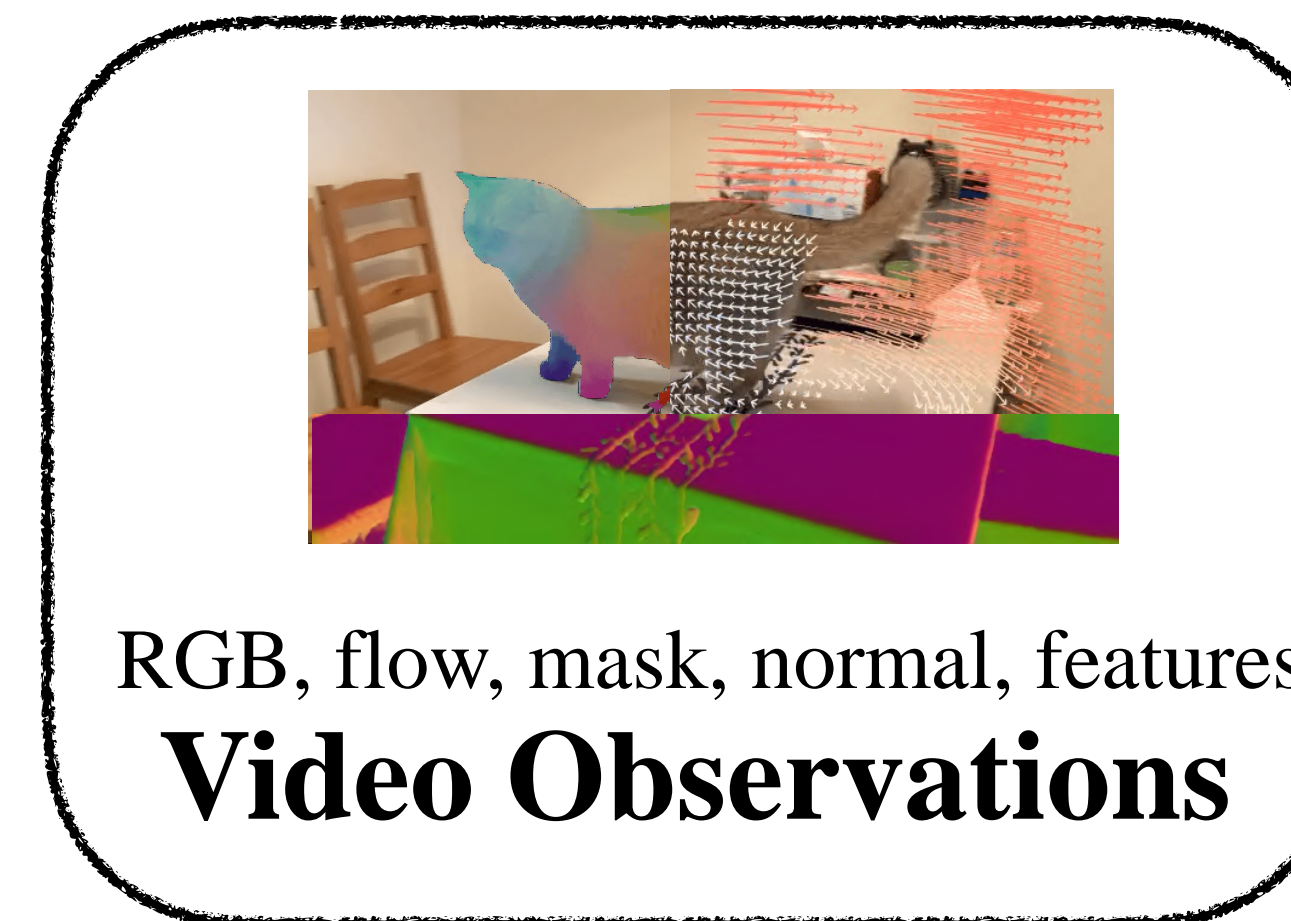
$\mathbf{T}$  : photometric parameters  
 $\mathbf{D}$  : kinematic parameters  
 $\phi$  : physical parameters

### Coordinate Descent

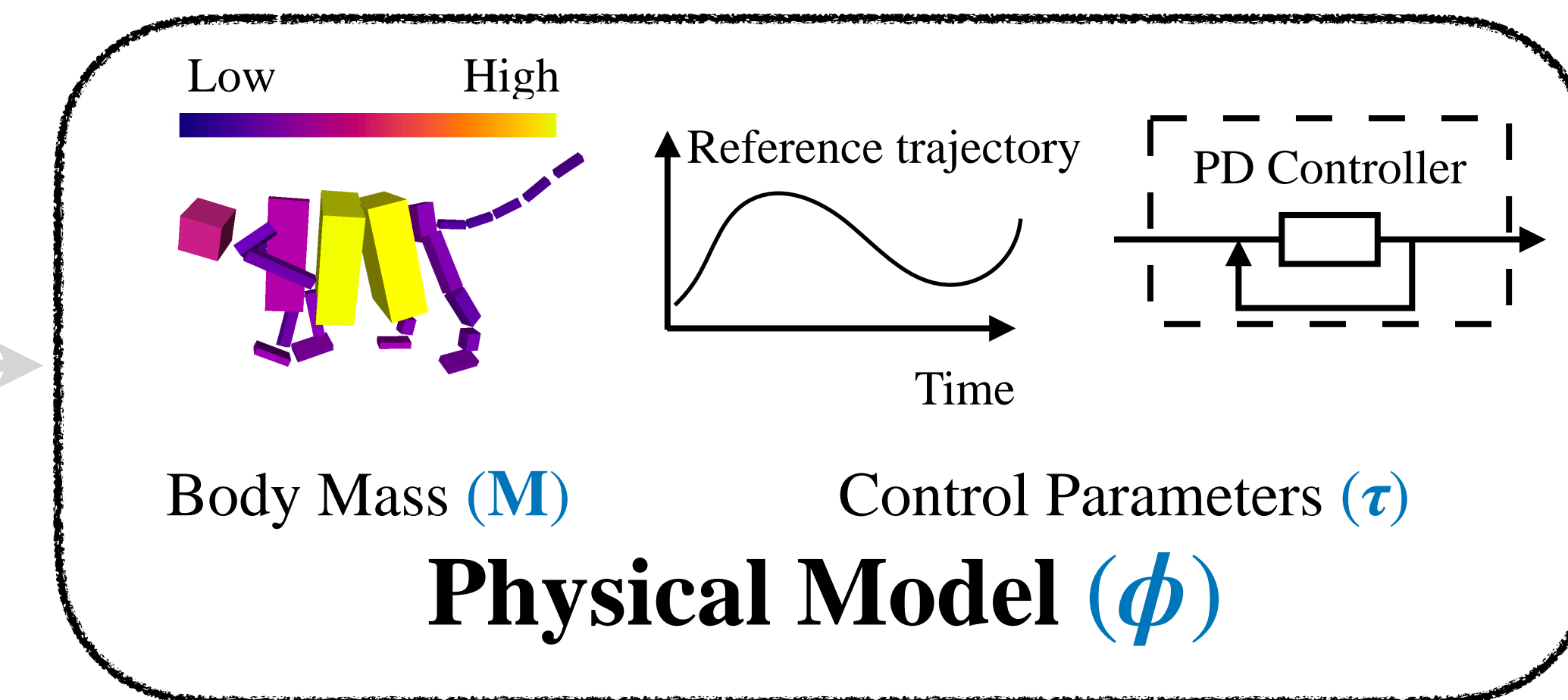
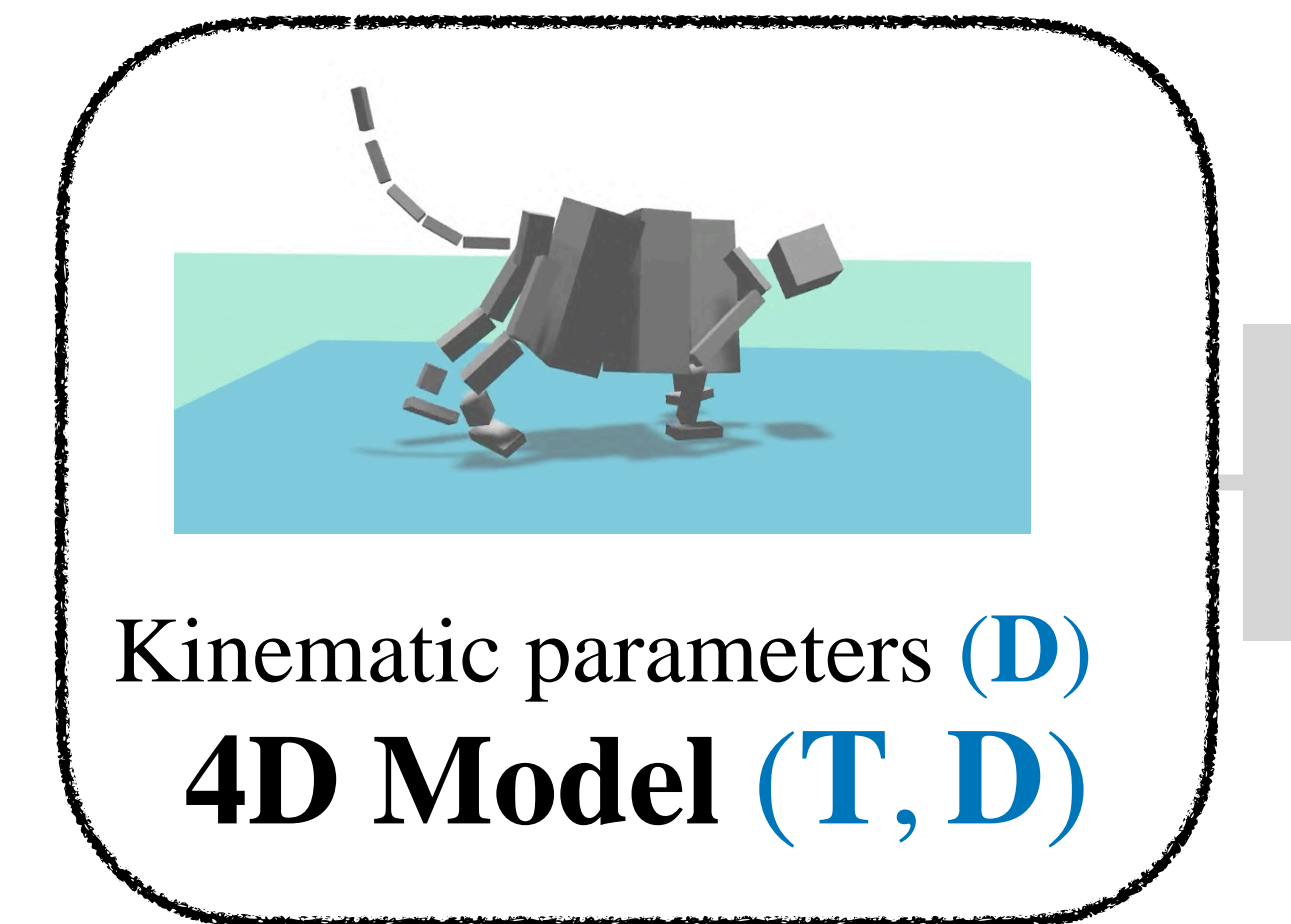
$$\min_{\mathbf{T}, \mathbf{D}} \mathcal{L}_{DR}(\mathbf{T}, \mathbf{D}) + \mathcal{L}_{DP}(\mathbf{D}, \phi)$$

$$\min_{\phi} \mathcal{L}_{DR}(\mathbf{T}, \mathbf{D}) + \mathcal{L}_{DP}(\mathbf{D}, \phi)$$

### Differentiable Rendering



### Differentiable Physics



## Qualitative Results

